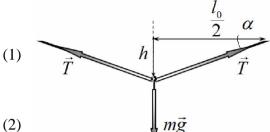
10

10-1.

1.

1.1

$$mg = 2T \sin \alpha.$$



$$T = kx = k \left(\frac{l_0}{2\cos\alpha} - \frac{l_0}{2} \right) = \frac{kl_0}{2} \left(\frac{1}{\cos\alpha} - 1 \right)$$
 (2)

$$mg = 2\frac{kl_0}{2} \left(\frac{1}{\cos \alpha} - 1 \right) \sin \alpha \quad \Rightarrow \quad \frac{1 - \cos \alpha}{\cos \alpha} \sin \alpha = \frac{mg}{kl_0}. \tag{3}$$

$$\frac{1 - \cos \alpha}{\cos \alpha} \sin \alpha \approx \frac{1 - \left(1 - \frac{\alpha^2}{2}\right)}{1 - \frac{\alpha^2}{2}} \alpha \approx \frac{\alpha^3}{2}$$

(3)

$$\alpha = \sqrt[3]{2 \frac{\text{mg}}{\text{kl}_0}} \tag{4}$$

$$h = \frac{l_0}{2} \operatorname{tg} \alpha \approx \frac{l_0}{2} \alpha = \frac{l_0}{2} \sqrt[3]{2 \frac{\operatorname{mg}}{\operatorname{kl}_0}}.$$

$$T \quad (1)$$

1.2

$$\begin{cases} \operatorname{mg} = 2\operatorname{T} \sin \alpha \\ \operatorname{T} = \frac{\operatorname{kl}_0}{2} \left(\frac{1}{\cos \alpha} - 1 \right) \end{cases} \Rightarrow \begin{cases} \operatorname{mg} = 2\operatorname{T}\alpha \\ \operatorname{T} = \frac{\operatorname{kl}_0}{2} \frac{\alpha^2}{2} \end{cases} \Rightarrow \begin{cases} (\operatorname{mg})^2 = 4\operatorname{T}^2\alpha^2 \\ \operatorname{T} = \frac{\operatorname{kl}_0}{2} \frac{\alpha^2}{2} \end{cases} \Rightarrow \frac{(\operatorname{mg})^2}{\operatorname{T}} = \frac{16\operatorname{T}^2}{\operatorname{kl}_0}$$

$$m_{\text{max}} = \frac{4}{g} \sqrt{\frac{F_{\text{max}}^3}{k l_0}}$$
 (6)

X

1

2.

2.1 O

 $a = \omega^2 R$.

 $(\Delta \varphi)$ $\Delta m \omega^2 R = 2T \frac{\Delta \varphi}{2}.$ (8)

 $\Delta m = \frac{m_0}{2\pi} \Delta \varphi \quad - \qquad . \tag{,}$

, , ,

$$T = \frac{m_0}{2\pi} \omega^2 R. (9)$$

AB,

,

: $T = k(2\pi R - l_0)$ (10)

(9)-(10) T,

$$T = \frac{kl_0}{\frac{4\pi^2 k}{m_0 \omega^2} - 1}$$

$$\frac{4\pi^2 k}{m_0 \omega^2} - 1 > 0$$
(11)

$$\tilde{\omega}_{\rm l} < 2\pi \sqrt{\frac{\rm k}{\rm m_0}} \tag{12}$$

2.2 , (12).

(11) F_{max} , (12) , (12) ,

 $F_{\text{max}} = \frac{kl_0}{\frac{4\pi^2 k}{m_0 \omega^2} - 1} \quad \Rightarrow \quad \tilde{\omega}_2 = 2\pi \sqrt{\frac{k}{m_0 \left(1 + \frac{kl_0}{F_{\text{max}}}\right)}}$ (13)

X . 1. 2

, (12).

2.3 (13), $k \Rightarrow \infty$.

 $\tilde{\omega} = 2\pi \sqrt{\frac{F_{\text{max}}}{m_0 l_0}} \tag{14}$

, (9),

10-2

1.

1.1 ,

$$c_1 \nu_1 T_1 + c_2 \nu_2 T_2 = (c_1 \nu_1 + c_2 \nu_2) \overline{\Gamma}$$
 (1)

$$PV = \nu RT , \qquad (2)$$

$$\nu T = \frac{PV}{R}$$
 $\nu = \frac{PV}{RT}$. (3)

(3),

3

$$\frac{3}{2}P_{1}V + \frac{5}{3}P_{2}V = \left(\frac{3}{2}\frac{P_{1}V}{T_{1}} + \frac{2}{2}\frac{P_{2}V}{T_{2}}\right)\overline{\Gamma}.$$
 (4)

 $\overline{T} = \frac{3 P_1 + 5 P_2}{\frac{3 P_1}{T_1} + \frac{5 P_2}{T_2}}.$ (5)

1.2 $C = \frac{3}{2}R\nu_1 + \frac{5}{2}R\nu_2 = \frac{3}{2}\frac{P_1V}{T_1} + \frac{3}{2}\frac{P_2V}{T_2}.$ (6)

$$\Delta T = \frac{Q}{C} \tag{7}$$

$$\frac{P + \Delta P}{T + \Delta T} = \frac{P}{T} \,. \tag{8}$$

. (8)

X . 1.

2020-2021

$$\frac{P + \Delta P}{T + \Delta T} = \frac{P}{T} \frac{1 + \frac{\Delta P}{P}}{1 + \frac{\Delta T}{T}} \approx \frac{P}{T} \left(1 + \frac{\Delta P}{P} - \frac{\Delta T}{T} \right). \tag{9}$$

(8)

$$\frac{\Delta P}{P} = \frac{\Delta T}{T} \tag{10}$$

$$\frac{\Delta P}{P} = \frac{\Delta T}{\overline{T}} = \frac{Q}{\frac{3}{2} \frac{P_1 V}{T_1} + \frac{3}{2} \frac{P_2 V}{T_2}} = \frac{2Q}{(3P_1 + 5P_2)V}$$
(11)

2.

2.1

$$\frac{5}{2}R\Delta T_0 = Q \quad \Rightarrow \quad \Delta T_0 = \frac{2Q}{5R} \,. \tag{12}$$

 ΔT .

$$v_1 = 2\eta v_0 = 2\alpha\Delta T$$
 (13)
 $(, v_0 = 1);$
 $v_2 = (1 - \eta)v_0 = 1 - \alpha\Delta T$ (14)

$$v_2 = (1 - \eta)v_0 = 1 - \alpha \Delta T \tag{14}$$

):

	$\frac{5}{2}$ RT ₀			
	Q			
			$\frac{3}{2}R \cdot 2\alpha\Delta T (T_0 + \Delta T) + $ $+ \frac{5}{2}R(1 - \alpha\Delta T)(T_0 + \Delta T)$	$\approx 3R\alpha T_0 \Delta T +$ $+ \frac{5}{2}R(T_0 + \Delta T + \alpha T_0 \Delta T)$ $= \frac{5}{2}RT_0 + \frac{5}{2}R\Delta T + \frac{11}{2}R\alpha T_0 \Delta T$
			q <i>α</i> ΔΤ	

X

« » 2020-2021

 $(\Delta T)^2$

. ,

$$\frac{5}{2}RT_{0} + Q = \frac{5}{2}RT_{0} + \frac{5}{2}R\Delta T + \frac{11}{2}R\alpha T_{0}\Delta T + q\alpha \Delta T.$$
 (15)

$$\Delta T = \frac{2Q}{5R + R\alpha T_0 + q\alpha}.$$
 (16)

2.3

--

3.

3.1 2 1 .

, 0,5 . . 0,5

:

$$2 \cdot \frac{5}{2} RT_0 + \frac{1}{2} q = \frac{6}{2} RT + \frac{1}{2} \cdot \frac{5}{2} RT . \tag{17}$$

$$T = \frac{20RT_0 + 2q}{17R}.$$
 (18)

q = 0

•

10-3.

1. .

1.1 $R = \rho_0 \frac{L}{S} = \rho_0 \frac{4L}{\pi l^2} = 0.87 \qquad . \tag{1}$

1.2 ,

,
$$r = \rho_1 \frac{h}{2\pi dL} = 6.7 \cdot 10^6 \quad . \tag{2}$$

2.

2.1 , I_0 , I_1 , I_2 , ...

X . 1. $U_0 \stackrel{R}{R} U_1 \stackrel{R}{V} \stackrel{R}{U}_2 \stackrel{R}{V}$

2020-2021

R

$$U_{k} = I_{k}R + U_{k+1}$$
 (3)

$$I_{k} = \frac{U_{k} - U_{k+1}}{R} \tag{4}$$

2.2

$$I_{k-1} = I_k + \frac{U_k}{r}.$$
 (5)

 $\frac{U_k}{r}$ -

(4) (5),

$$\frac{U_{k-1} - U_k}{R} = \frac{U_k}{r} + \frac{U_k - U_{k+1}}{R} \,. \tag{6}$$

$$U_{k-1} - \left(2 + \frac{R}{r}\right) U_k + U_{k+1} = 0.$$
 (7)

2.3

$$U_{k} = U_{0} \lambda^{k}$$

$$U_{0} \lambda^{k-1} - \left(2 + \frac{R}{r}\right) U_{0} \lambda^{k} + U_{0} \lambda^{k+1} = 0.$$
(8)

$$\lambda^2 - \left(2 + \frac{R}{r}\right)\lambda + 1 = 0. \tag{9}$$

(9).
$$\lambda_{1,2} = 1 + \frac{R}{2r} \pm \sqrt{\left(1 + \frac{R}{2r}\right)^2 - 1}$$
 (10)

1.

 $\lambda = 1 - \varepsilon$, $\varepsilon = 3.6 \cdot 10^{-4}$.

 $\lambda = 1 + \frac{R}{2r} - \sqrt{\left(1 + \frac{R}{2r}\right)^2 - 1} = 1 + \frac{R}{2r} - \sqrt{\frac{R}{r} + \left(\frac{R}{2r}\right)^2} \approx 1 - \sqrt{\frac{R}{r}}$

2020-2021 10-3.

1.

1.1

$$R = \rho_0 \frac{L}{S} = \rho_0 \frac{4L}{\pi d^2} = 0.87 \qquad . \tag{1}$$

1.2

$$r = \rho_1 \frac{h}{2\pi dL} = 6.7 \cdot 10^6 \qquad . \tag{2}$$

2.

2.1

R $\mathbf{U}_{k} = \mathbf{I}_{k} \mathbf{R} + \mathbf{U}_{k+1}$

> $I_{k} = \frac{U_{k} - U_{k+1}}{R}$ (4)

2.2

,
$$I_{k-1} = I_k + \frac{U_k}{r}.$$
(5)

 $\frac{U_k}{r}$ -

(4) (5),

$$\frac{\mathbf{U}_{k-1} - \mathbf{U}_{k}}{\mathbf{R}} = \frac{\mathbf{U}_{k}}{\mathbf{r}} + \frac{\mathbf{U}_{k} - \mathbf{U}_{k+1}}{\mathbf{R}}.$$
 (6)

$$U_{k-1} - \left(2 + \frac{R}{r}\right)U_k + U_{k+1} = 0.$$
 (7)

2.3

 $\mathbf{U}_{k} = \mathbf{U}_{0} \lambda^{k}$ $U_{0}\lambda^{k} \qquad (7):$ $U_{0}\lambda^{k-1} - \left(2 + \frac{R}{r}\right)U_{0}\lambda^{k} + U_{0}\lambda^{k+1} = 0.$ (8)

> $\lambda^2 - \left(2 + \frac{R}{r}\right)\lambda + 1 = 0.$ (9)

X 7

2020-2021 $\lambda_{1,2} = 1 + \frac{R}{2r} \pm \sqrt{\left(1 + \frac{R}{2r}\right)^2 - 1}$ (10)1. $\varepsilon = 3.6 \cdot 10^{-4} .$ 10^{-8} , 10^{-8} . (10) $\lambda = 1 + \frac{R}{2r} - \sqrt{\left(1 + \frac{R}{2r}\right)^2 - 1} = 1 + \frac{R}{2r} - \sqrt{\frac{R}{r} + \left(\frac{R}{2r}\right)^2} \approx 1 - \sqrt{\frac{R}{r}}$ 0,5. (10)2.4 1 N = 20002000 $\frac{\mathrm{U}_{2000}}{\mathrm{U}_{0}} = (1 - \varepsilon)^{\mathrm{N}} \approx 0.5$ (11)2 10 0,5. (10)2.5 N = 20002000 $\frac{\mathrm{U}_{2000}}{\mathrm{U}_{0}} = (1 - \varepsilon)^{\mathrm{N}} \approx 0.5$ (11)2 10

X . 1.

8